# Summary of NASA OCT Science Instrument, Observatory and Sensor System (SIOSS) Technology Assessment Roadmap.

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#### Agenda

Office of Chief Technologist Technology Assessment A-STAR

Technology Assessment #8: Science Instruments, Observatories and Sensor Systems

## Aero-Space Technology Area Roadmap (A-STAR)

July 2010, NASA Office of Chief Technologist (OCT) initiated an activity to create and maintain a NASA integrated roadmap for 15 key technology areas which recommend an overall technology investment strategy and prioritize NASA's technology programs to meet NASA's strategic goals.

Initial reports were presented to the National Research Council who are currently collecting public input and preparing reviews of each Roadmap.

Roadmaps will be updated annually and externally reviewed every 4 years consistent with the Agency's Strategic Plans.

#### **Technology Assessment Areas**

TA1: Launch Propulsion Systems

TA2: In-Space Propulsion Systems

TA3: Space Power and Energy Storage Systems

TA4: Robotics, Tele-robotics, and Autonomous Systems

TA5: Communication and Navigation Systems

TA6: Human Health, Life Support and Habitation Systems

TA7: Human Exploration Destination Systems

TA8: Scientific Instruments, Observatories, and Sensor Systems

TA9: Entry, Descent, and Landing Systems

TA10: Nanotechnology

TA11: Modeling, Simulation, Information Technology, and Processing

TA12: Materials, Structural & Mechanical Systems, and Manufacturing

TA13: Ground and Launch Systems Processing

TA14: Thermal Management Systems

TA15: Aeronautics

#### Goals and Benefits

External credibility for planned NASA technology programs
Internally credible and transparent process to ensure all Mission
Directorate (MD) priorities are included

Develop clear NASA technology portfolio recommendations

Establish current prioritization of alternate technology paths

Reveal interrelationships of various technologies and associated investments

Interrelationships and coordination with other agencies

Broad-based input from non-government parties

Transparency in government technology investments

#### Charge to TA Teams

Review, document, and organize the existing roadmaps and technology portfolios.

Collect input from key Center subject matter experts, program offices and Mission Directorates.

#### Take into account:

US aeronautics and space policy;

NASA Mission Directorate strategic goals and plans;

Existing Design Reference Missions, architectures and timelines; and

Past NASA technology and capability roadmaps.

#### **Technology Assessment Content**

Define a breakdown structure that organizes and identifies the TA Identify and organize all systems/technologies involved in the TA using a 20-year horizon

Describe the state-of-the-art (SOA) for each system
Identify the various paths to achieve performance goals
Identify NASA planned level of investment
Assess gaps and overlaps across planned activities
Identify alternate technology pathways
Identify key challenges required to achieve goals

## Technology Assessment #8:

# Science Instruments, Observatories and Sensor Systems (SIOSS)

SIOSS technology needs & challenges are traceable to: specific NASA science missions planned by the Science Mission Directorate ('pull technology') or emerging measurement techniques necessary to enable new scientific discovery ('push technology').

#### TA8 Roadmap Team

Rich Barney (GSFC), Division Chief, Instrument Systems and Technology Division.

Co-chaired 2005 NASA Science Instruments and Sensors Capability Roadmap.

Phil Stahl (MSFC), Senior Optical Physicists

Optical Components Technical Lead for James Webb Space Telescope;

Mirror Technology Days in the Government;

Advanced Optical Systems SBIR Subtopic Manager;

2005 Advanced Observatories and Telescopes Capability Roadmap.

Upendra Singh (LaRC), Chief Technologist, Engineering Directorate.

Principal Investigator for NASA Laser Risk Reduction Program (2002-2010)

Dan Mccleese (JPL), Chief Scientist

Principal Investigator of Mars Climate Sounder instrument on Mars Reconnaissance Orbiter.

Jill Bauman (ARC), Associate Director of Science for Mission Concepts.

Lee Feinberg (GSFC), Chief Large Optics System Engineer

JWST OTE Manager.

Co-chaired 2005Advanced Telescopes and Observatories Capability Roadmap.

## Technology Assessment Breakdown Structure (TABS)

The most difficult task was defining a TABS.

SIOSS is a merger of the 2005 NASA Advanced Planning and Integration Office (APIO) roadmaps:

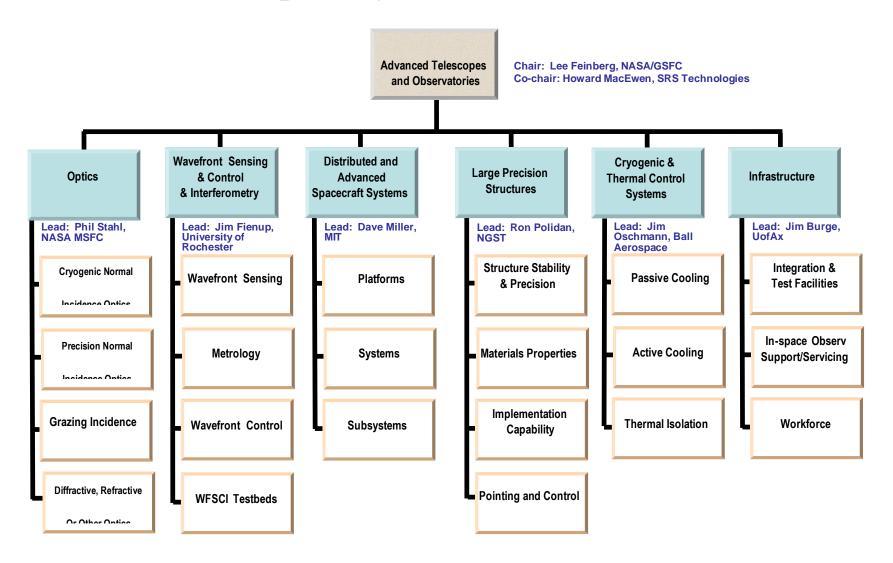
Advanced Telescopes and Observatories (ATO), and Science Instruments and Sensors (SIS).

But, ATO and SIS had approached Capability Assessment with from two entirely different methodologies.

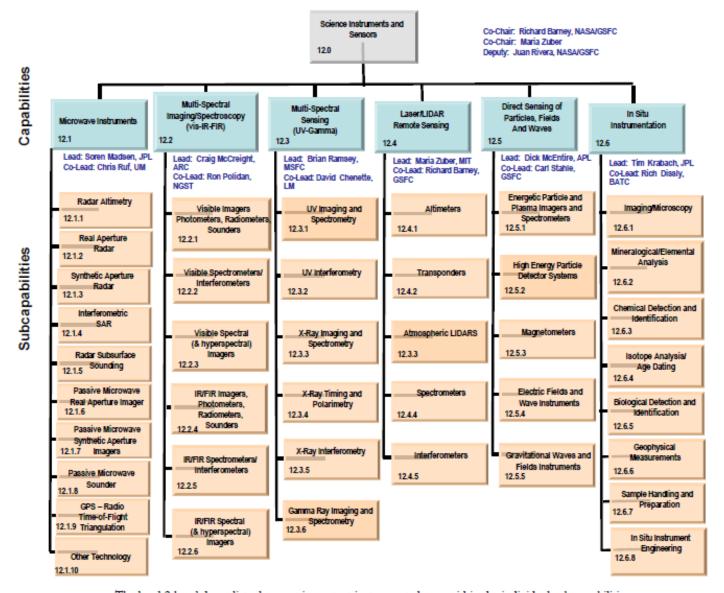
ATO was technology driven.

SIS was measurement driven.

## ATO Capability Breakdown Structure



#### SIS Capability Breakdown Structure



The level 2-breakdown lists the most important instrument classes within the individual sub-capabilities.

#### SIOSS TABS

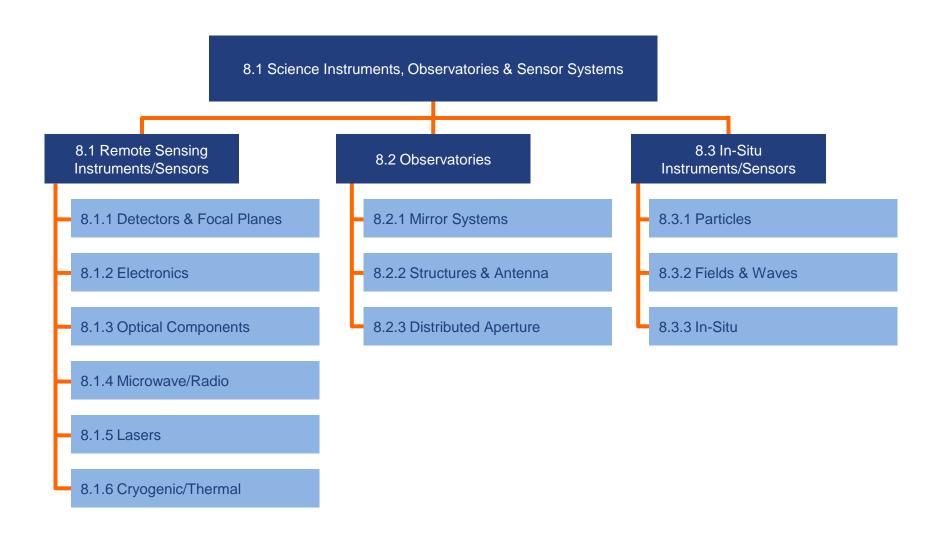
We defined a three-tier TABS based on the name we were given.

Science Instrument technologies generate photons or convert photons into science data. They may be stand-alone sharing a common spacecraft bus or integrated with an observatory.

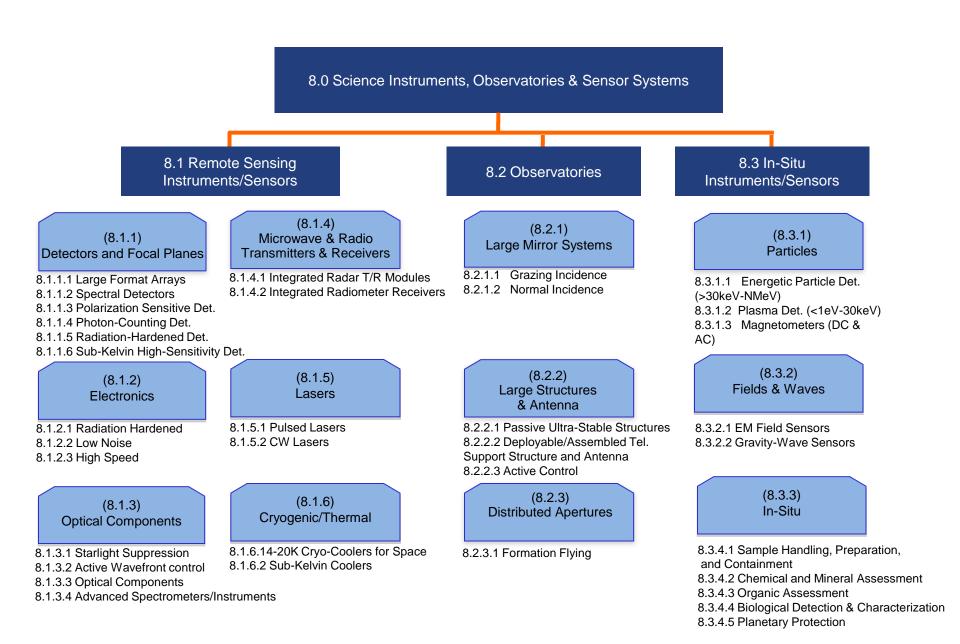
Observatory technologies collect, concentrate, and/or transmit photons.

Sensor System technologies create data by collecting and sensing particles, fields, waves, chemicals, or biological samples and are stand-alone systems not requiring an observatory.

## TA8: Technology Area Breakdown Structure



## TA8: Technology Area Breakdown Structure



## SIOSS Team employed a two-step process

First step was to review existing governing documents (such as Decadal Surveys, roadmaps, and the science plans) for each of the four NASA Science Mission Directorate (SMD) divisions:

Astrophysics, Earth Science,

Heliophysics, Planetary.

From these, specific technology needs were identified that enable or enhance planned and potential future missions.

Detailed listings of technology needs for each SMD division were tabulated and then reviewed and refined by individual mission and technology-development stakeholders.

#### Astrophysics Technology Needs

National Academy 2010 Decadal Report recommended missions and technology-development programs, (with need date):

Wide Field Infrared Survey Telescope (WFIRST), 2018

Explorer Program, 2019/2023

Laser Interferometer Space Antenna (LISA), 2024

International X-ray Observatory (IXO), mid/late 2020s

New Worlds Technology Development Program, mid/late 2020s

Epoch of Inflation Technology Development Program, mid/late 2020s

U.S. Contribution to the JAXA-ESA SPICA Mission, 2017

UV-Optical Space Capability Technology Development Program, mid/late 2020s

TRL3-to-5 Intermediate Technology Development Program

All can be enhanced or enabled by technology development to reduce cost, schedule, and performance risks.

## Astrophysics Technology Needs

#### Astrophysics requires advancements in 5 SIOSS areas:

Detectors and electronics for X-ray and UV/optical/infrared (UVOIR);

Optical components and systems for starlight suppression, wavefront control, and enhanced UVOIR performance;

Low-power sub 10K cryo-coolers;

Large X-ray and UVOIR mirror systems; and

Multi-spacecraft formation flying, navigation, and control.

#### Additionally, Astrophysics missions require other technologies:

Affordable volume and mass capacities of launch vehicles to enable largeaperture observatories and mid-capacity missions;

Terabit communication; and

Micro-Newton thrusters for precision pointing and formation-flying navigation control.

Table 2.2.1.1 – 1 Summary of Astrophysics Technology Needs							
Mission	Technology	Metric	State of Art	Need	Start	TRL6	
WFIRST	NIR detectors	Pixel array	2k x 2k	4k x 4k	2012	2014	
		Pixel size	18 μm	10 μm			
UVOTP	Detector arrays:	Pixel	2k x 2k	4k x 4k	2012	2020	
Push	Low noise	QE UV		> 0.5 90-300 nm			
		QE Visible		> 0.8 300-900 nm			
		Rad Hard		50 to 200 kRad			
NWTP	Photon counting arrays	Pixel array visible	512 x 512	1k x 1k	2011	2020	
Push		Visible QE	80% 450-750 nm	>80% 450-900 nm			
CDICA	E m i	Pixel array NIR	128 x 128	256 x 256	2011	2015	
SPICA	Far-IR detector arrays	Sens. (NEP W/√Hz)	1e-18	3e-20	2011	2015	
ITP December		Wavelength	> 250μm	35-430μm		2020	
Push	X 1	Pixels	256	1k x 1k	2011	2015	
IXO	X-ray detectors	Pixel array	10 15 - DMC	40 x 40 TES	2011	2015	
Push		Noise	10-15 e <sup>-</sup> RMS	2-4 e <sup>-</sup> RMS			
		QE Frame rate	100 kHz@2e <sup>-</sup>	>0.7 0.3-8 keV 0.5 - 1 MHz@2e <sup>-</sup>			
WFIRST	Detector ASIC	Speed @ low noise	100 kHz@2e	0.5 - 1 MHz@2e	2011	2013	
IXO	Detector ASIC	Rad tolerance	14 krad	55 krad	2011	2013	
NWTP	Visible Starlight	Contrast	> 1 x 10 <sup>-9</sup>	$< 1 \times 10^{-10}$	2011	2016	
NWIF	suppression:	Contrast stability	> 1 X 10	1 x 10 <sup>-11</sup> /image	2011	2020	
	coronagraph or	Passband	10%, 760-840 nm	20%, at <i>V</i> , <i>I</i> , and <i>R</i>	2011	2020	
	occulter	Inner Working Angle	4 λ/D	$2\lambda/D - 3\lambda/D$			
NWTP	Mid-IR Starlight	Contrast	1.65 x 10 <sup>-5</sup> , laser	$< 1 \times 10^{-7}$ , broadband	2011	2016	
14 44 11	suppres: interferometer	Passband mid-IR	30% at 10 μm	> 50% 8μm	2011	2020	
NWTP	Active WFSC:	Sensing Sensing	$\lambda/10,000 \text{ rms}$	$< \lambda/10,000 \text{ rms}$	2011	2020	
UVOTP	Deformable Mirrors	Control (Actuators)	32 x 32	128 x 128	2011	2020	
IXO	XGS CAT grating	Facet size; Throughput	3x3 mm; 5%	60x60mm; 45%	2010	2014	
Various	Filters & coatings	Reflect/transmit; temp	3A3 IIIII, 370	00X00IIIII, 4370	2011	2020	
Various	Spectroscopy	Spectral range/resolve			2011	2020	
SPICA	Continuous sub-K	Heat lift	< 1 µW	> 1 µW	2011	2015	
IXO	refrigerator	Duty cycle	90 %	100 %	2011	2013	
IXO	Large X-ray mirror	Effective Area	0.3 m2	>3 m2 (50 m2)	2011	2020	
Push	systems	HPD Resolution	15 arcsec	<5 arcsec (<1 as)	2011	(30)	
		Areal Density; Active	10 kg/m2; no	1 kg/m2; yes		()	
NWTP	Large UVOIR mirror	Aperture diameter	2.4 m	3 to 8 m (15 to 30 m)	2011	2020	
UVOTP	systems	Figure	< 10 nm rms	<10 nm rms		(30)	
Push		Stability		>9,000 min		` '	
		Reflectivity	>60%, 120-900 nm	>60%, 90-1100 nm			
		kg/m2	30 kg/m2	Depends on LV			
		\$/m2	\$12M/m2	<\$1M/m2			
WFIRST	Passive stable structure	Thermal stability	Chandra	WFOV PSF Stable	2011	2014	
NWTP	Large structure: occulter	Dia; Petal Edge Tol	Not demonstrated	30-80 m; <0.1mm rms	2011	2016	
NWTP	Large, stable telescope	Aperture diameter	6.5 m	8 m (15 to 30 m)	2011	2020	
UVOTP	structures	Thermal/dynamic WFE	60 nm rms	< 0.1 nm rms		(30)	
Push	(Passive or active)	Line-of-sight jitter	1.6 mas	1 mas			
		kg/m2	40 kg/m2	<20 (or 400) kg/m2			
		\$/m2	\$4 M/m2	<\$2 M/m2			
LISA	Drag-Free Flying	Residual accel	$3x10^{-14} \text{ m/s}^2/\sqrt{\text{Hz}}$	$3x10^{-15} \text{ m/s}^2/\sqrt{\text{Hz}}$	2011	2016	
NWTP	Occulter Flying	Range		10,000 to 80,000 km			
		Lateral alignment		±0.7 m wrt LOS			
NWTP	Formation flying:	Position/pointing	5cm/6.7arcmin		2011	2020	
Push	Sparse & Interferometer	#; Separation	2; 2; 2 m	5; 15–400-m	2012	2010	
LISA	Gravity wave sensor	Spacetime Strain	N/A	1x10 <sup>-21</sup> /√Hz, 0.1-	2013	2019	
Push	Atomic interferometer	Bandpass		100mHZ		2011	
Various	Communication	Bits per sec		Terra bps		2014	

## SIOSS Team employed a two-step process

Second step was consolidating the detailed technology needs for each mission directorate into broad categories. For example, many missions across all directorates require new or improved detector technology.

These broad categories were then organized into a Technology Area Breakdown Structure (TABS).

## Technology Area 8.2 Observatory

#### Major challenges include:

X-ray Grazing Incidence Mirror Systems
UV-Vis-IR Normal Incidence Mirror Systems
Large Ultra-stable Structures
Large Deployable/Assembled Structures
Control of Large Structures
Distributed Aperture / Formation flying

#### Technologies support 3 applications:

X-ray astronomy,

UVOIR astronomy, and

Radio / microwave antenna.

Most important metric for all observatories is cost per square meter of aperture.

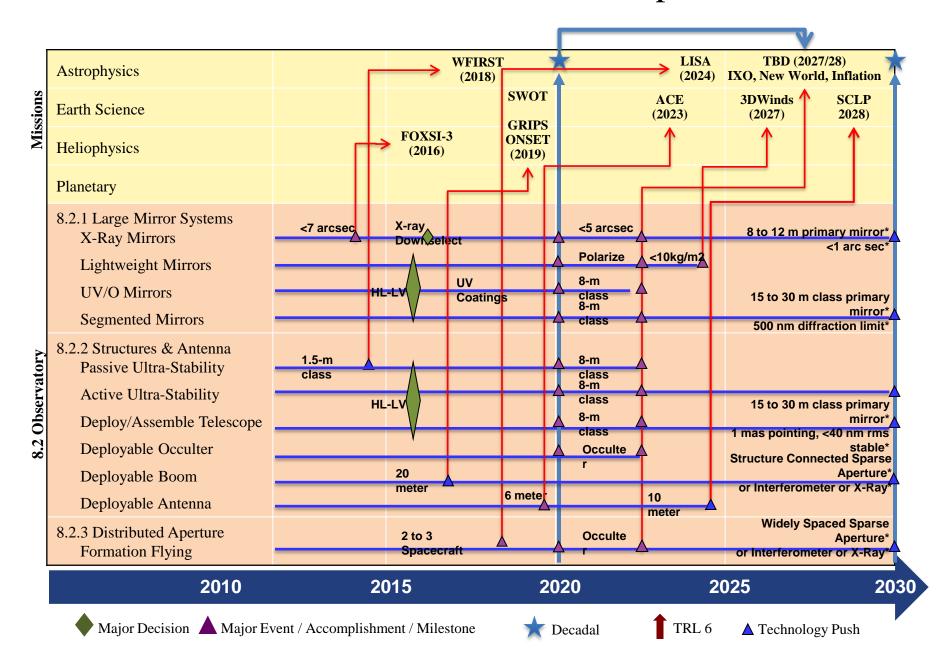
	ble 2.2.2.2-1: Observatory T Technology Metric	State of Art	Need	Start	TRL6	Missio	
	8.2.1.1 Grazing Incidence						
	1 to 100 keV FWHM resolution	10 arcsec	<5 arcsec	2011	2014	FOXSI	
	Aperture diameter	0.3 m2	>3 m2	2011	2020	IXO	
	FWHM resolution	15 arcsec	<5 arcsec				
	Areal density; Areal cost	10 kg/m2					
	Aperture diameter	0.3 m2	>50 m2	2011	2030	Push	
	FWHM angular resolution	15 arcsec	<1 arcsec			GenX	
	Areal density (depends on LV)	10 kg/m2	1 kg/m2 (depend LV)				
	Active Control	No	Yes				
	8.2.1.2 Normal Incidence						
S	Size & polarization	Planck	1.6 m	2011	2020	ITP	
E	Areal density	~20 kg/m2	<6 kg/m2	2018	2024	3DWi	
yst S	Aperture diameter	2.4 m	3 to 8 m	2011	2020	NWT	
r S	Figure	< 10 nm rms	<10 nm rms			UVO	
Ĕ	Stability (dynamic & thermal)		>9,000 min				
Ξ	Reflectivity	>60%, 120-900nm	>60%, 90-900 nm				
8.2.1 Large Mirror Systems	Areal density (depends on LV)	240 kg/m2	20 (or 400) kg/m2				
Ę,	Areal cost	\$12M/m2	<\$2M/m2		2020	D1.	
Ξ.	Aperture diameter Areal density (depends on LV)	6.5 m 50 kg/m2	15 to 30 m 5 (or 100) kg/m2		2030	Push EL-ST	
×	Areal cost	\$6M/m2	< \$0.5M/m2			EL-31	
	8.2.2.1 Passive Ultra-Stable Structures						
	Thermal stability	Chandra	WFOV PSF Stability	2011	2014	WFIR	
	Aperture diameter	6.5 m	8 m	2011	2020	NW/U	
	Thermal/dynamic stability	60 nm rms	15 nm rms	2011	2020	1111/6	
	Line-of-sight jitter WFE	1.6 mas	1 mas				
	Areal density (depends on LV)	40 kg/m2	<20 (or 400) kg/m2				
	Areal cost	\$4 M/m2	<\$2 M/m2				
	8.2.2.2 Deployable/Assembled Telescope Support Structure and Antenna						
	Antenna aperture	5 m	6 m	2013	2019	ACE	
	Antenna aperture		> 10 m	2016	2023	SCLP	
	Surface figure	1.5 mm rms	<0.1 mm rms				
	Boom length		≥ 20 m	2011	2014	GRIPS	
	Stiffness		10 <sup>7</sup> N m <sup>2</sup>			ONEF	
	Pointing stability		0.005 arcsec roll/3 min			SWO	
ಡ	Occulter diameter	Few cm	30 to 100 m	2011	2020	NWT	
ue	Aperture diameter	6.5 m	8 m	2011	2020	NW/U	
Ĩ	Aperture diameter	6.5 m	15 to 30 m		2030	EL-ST	
×	8.2.2.3 Active Control						
8.2.2 Large Structures & Antenna	Occulter pedal control		< 0.5 deg	2011	2020	NWTI	
	Occulter modal control		< 0.1 mm rms	2012	2014	GRIPS	
	Boom tip control		~0.5 deg				
	Aperture diameter	6.5 m 6.5 m	8 m 15 to 30 m	2011	2020	NW/U	
	Aperture diameter Thermal/dynamic stability	6.5 m 60 nm rms	15 to 30 m 15 nm rms		2030	Push EL-ST	
	Line-of-Sight jitter WFE	1.6 mas	15 nm rms 1 mas		1	EL-31	
	Areal density (depends on LV)	40 kg/m2	<20 (or 400) kg/m2		1		
	Areal cost	\$4 M/m2	<\$2 M/m2		1		
	8.2.3.1 Formation Flying						
	Range		10,000 to 80,000 km	2013	2016	LISA	
8.2.3 Distributed	Separation control	2 m	100 to 400 ±0.1 m	2013	2015	ONE	
	Lateral alignment	2 111	±0.7 m wrt LOS	2011	2013	Occult	
	Relative position	5 cm rms	< 1 cm rms		2024	NWTI	
	Relative pointing	6.7 arcmin rms	< 1 ±0.1 arcsec	1	2030	Push	

Technology Metric   State of Art   Need   Start   TRL6   Mission	Tah	Table 2.2.2.2-1: Observatory Technology Challenges							
Reflectivity					Start	TRL6	Mission		
To 100 keV FWHM resolution   10 arcsec									
Aperture diameter   0.3 m2   >3 m2   <2011   2020   IXO			10 arcsec	<5 arcsec	2011	2014	FOXSI-3		
FWHM resolution			0.3 m2		2011		IXO		
Aperture diameter   0.3 m2			15 arcsec	<5 arcsec					
FWHM angular resolution		Areal density; Areal cost	10 kg/m2						
Areal density (depends on LV)  Active Control  8.2.1.2 Normal Incidence  8.2.1.2 Normal Incidence  8.2.1.2 Normal Incidence  8.2.2.2 Polarization  Areal density — 20 kg/m2 — 40 kg/m2 — 2018 — 2024 — 3DWinds  Aperture diameter — 2.4 m — 3 to 8 m — 2011 — 2020 — NWTP  Figure — 10 nm rms — 10 nm rms — 9,000 nmi  Areal density (depends on LV) — 560%, 120-900nm  Areal density (depends on LV) — 40 kg/m2 — 20 (or 400) kg/m2 — 40 kg/m2 — 20 (or 400) kg/m2 — 40 kg/m2			0.3 m2	>50 m2	2011	2030	Push		
Active Control   No   Yes							GenX		
Size & polarization									
Size & polarization			No	Yes					
Areal density									
Real cost   Solve	St								
Real cost   Solve	ten								
Real cost   Solve	sys				2011	2020			
Real cost   Solve	ır S	Figure					UVOTP		
Real cost   Solve	iiro			*					
Real cost   Solve	N N								
Real cost   Solve	ırge			, ,					
Real cost   Solve	$\Gamma_{\epsilon}$					2030	Duch		
Real cost   Solve	2.1					2030			
R.2.2.1 Passive Ultra-Stable Structures   Thermal stability	8.			< \$0.5M/m <sup>2</sup>			LL 51		
Thermal stability				ζ ψ0.5141/1112	<u>l</u>				
Aperture diameter				WFOV PSF Stability	2011	2014	WFIRST		
Thermal/dynamic stability   Line-of-sight jitter WFE   Areal density (depends on LV)   40 kg/m2   <20 (or 400) k									
Line-of-sight jitter WFE   1.6 mas   1 mas   20 (or 400) kg/m2   40 kg/m2					2011	2020	1111/010		
Areal density (depends on LV)									
Areal cost   \$4 M/m2   <\$2 M/m2			40 kg/m2	<20 (or 400) kg/m2					
Antenna aperture Antenna aperture Surface figure  1.5 mm rms    Antenna aperture   Surface figure   Surface		Areal cost							
Antenna aperture Surface figure    Surface figure   1.5 mm rms   201 mm rms   201   2014   GRIPS									
Surface figure   1.5 mm rms			5 m			2019	ACE		
Boom length   Stiffness   Pointing stability   Coculter diameter   Few cm   30 to 100 m   2011   2020   NWTP					2016	2023	SCLP		
Stiffness   10 <sup>7</sup> N m <sup>2</sup>   0.005 arcsec roll/3 min   SWOT			1.5 mm rms						
Pointing stability				$\geq 20 \text{ m}$	2011	2014			
Occulter diameter   Few cm   30 to 100 m   2011   2020   NWTP									
Aperture diameter				0.005 arcsec roll/3 min					
Aperture diameter	за								
Aperture diameter	eni			-	2011				
Aperture diameter	Ant		6.5 m	15 to 30 m		2030	EL-ST		
Aperture diameter	8,								
Aperture diameter	es.								
Aperture diameter	:tm				2012	2014	GRIPS		
Aperture diameter	Struc		( F		2011	2020	NW/IWO		
Thermal/dynamic stability Line-of-Sight jitter WFE					2011				
Line-of-Sight jitter WFE Areal density (depends on LV)	ırga					2030			
Areal density (depends on LV)	Ľ						EL-51		
Real Cost   34 N/m2   <32 N/m2	2.2			****					
8.2.3.1 Formation Flying           Range         10,000 to 80,000 km         2013         2016         LISA           Separation control         2 m         100 to 400 ±0.1 m         2011         2015         ONEP           Lateral alignment         ±0.7 m wrt LOS         Occulter           Relative position         5 cm rms         < 1 cm rms	8.								
Range         10,000 to 80,000 km         2013         2016         LISA           Separation control         2 m         100 to 400 ±0.1 m         2011         2015         ONEP           Lateral alignment         ±0.7 m wrt LOS         Occulter         Occulter           Relative position         5 cm rms         < 1 cm rms			ψ. 141/1112						
Separation control Lateral alignment Relative position  2 m 100 to 400 ±0.1 m ±0.7 m wrt LOS <1 cm rms 2011 2015 ONEP Occulter NWTP				10,000 to 80,000 km	2013	2016	LISA		
Lateral alignment ±0.7 m wrt LOS Occulter Relative position 5 cm rms	601		2 m						
Relative position 5 cm rms < 1 cm rms 2024 NWTP	8.2.3		===						
$\infty$ Relative pointing 6.7 arcmin rms $< 1 \pm 0.1$ arcsec 2030 Push			5 cm rms			2024			

# Push Technologies: 8.2 Observatories

Technology	Description
8.2 Observatories	
Synthetic Aperture Imaging Lidar (SAIL)	Synthetic Aperture Imaging Lidar (SAIL) for hyper-resolution imaging and 3D ranging (range imaging). SAIL methods could map dynamics of planetary surfaces on Mars (polar caps), Titan (moving landscapes), and even on Europa much more efficiently than current single beam or multi-beam approaches. SAIL may be a method worth pursuing for ICESat-3 in the 2020's to rapidly build up 3D geodetic maps of the ice covered surfaces of Earth
Super High-Resolution Imaging of High-Energy Photons	The technology need is to build a large area (much larger than current optics) high energy optic and then have it fly it formation with the imaging spacecraft
Radar Arrays	Wideband active electronically steered array radar with lightweighted antennae
Precision Interferometry	Requires CW single-frequency and frequency-stabilized lasers for space (GSFC applications so far are pulsed). Digital techniques including coded modulation for time-of-flight resolvable interference, and flexible in-flight changes. Time-Domain Interferometry (LISA's equal-path-length synthesis techniques).
Hyper-Resolution Visible- NIR	Hyper-resolution Visible-NIR imaging using lightweighted optics in the 1-1.5m class (5 cm/pixel class)
K-Band Radar	Compact K-band imaging and sounding radars (nadir and sidelooking) for planetary sciences (small antennae)
Conductive Carbon Nanotubes	Spectacular new material for the fabrication of lightweight antennas could be enabled by the unbelievable conductivity of individual carbon nanotubes.
Deployable Large Aperture Telescopes	Ultra low mass/volume large deployable large aperture telescopes (>2 meter) for direct detection LIDAR. Concepts include inflatable fresnel, deployable reflector and petal-based techniques.
High stability optical platforms	Includes optical benches, telescopes, etc, requiring passive thermal isolation for temperature stability. Hydroxide or silicate bonding for precision alignment capability and dimensional stability. Precision materials such as Silicon Carbide and single crystal silicon, Zerodur

#### 8.2 Observatories Roadmap



#### Observatory Technology Needs

Regardless of whether the incumbent is 0.5 m or 5 m, the driving need is larger aperture with similar or better performance.

The technologies for achieving performance are

the ability to manufacture and test large-mirror systems;

the structure's ability to hold the mirror in a stable, strain-free state under the influence of anticipated dynamic and thermal stimuli; and,

for extra-large apertures, a method to create the aperture via deployment, assembly, or formation flying – where formation-flying technology is simply an actively controlled virtual structure.

One non-telescope application is the manufacture, deployment, in-plane and formation-flying control of an external-occulting starshade to block starlight for exo-planet observation.

## Top Mirror Technology Challenges

#### Present to 2016 (Near Term)

Low-Cost, Large-Aperture Precision Mirrors

UV and optical lightweight mirrors, 5 to 10 nm rms, <\$2M/m2, <30kg/m2

X-ray: <5 arc sec resolution, < \$0.1M/m2 (surface normal space), <3 kg/m2

#### 2017 to 2022 (Mid Term)

High-Contrast Exoplanet Technologies

High-contrast nulling and coronagraphic algorithms and components ( $1x10^-10$ , broadband); occulters (30 to 100 meters, < 0.1 mm rms)

Ultra-Stable Large Aperture UV/O Telescopes

> 50 m2 aperture, < 10 nm rms surface, < 1 mas pointing, < 15 nm rms stability, < \$2M/m2

## Other Technology Assessment Observatory Needs

The ability to produce large aperture observatories depends upon advances in other technology assessment areas:

- volume and mass capacities of launch vehicles;
- validated performance models that integrate optical, mechanical, dynamic, and thermal models for telescopes, structures, instruments, and spacecraft to enable the design and manufacture of observatories whose performance requirements are too precise to be tested on the ground;
- new materials and design concepts to enable ultra-stable very large space structures;
- terabit communication; and
- autonomous rendezvous and docking for on-orbit assembly of very large structures.

#### Benefits to Other National Needs

SIOSS Technologies have potential benefit for a wide range of national needs, organizations and agencies:

- National Atmospheric and Oceanic Administration (NOAA)
- Department of Defense (DoD)
- Commercial Space Imaging Companies
- Department of Homeland Security (DHS)
- Department of Energy
- Department of Health and Human Services
- Food and Drug Administration
- Environmental Protection Agency

## Summary

Science Instruments, Observatories, and Sensor System Technology Area 8 Roadmap draft is complete and currently undergoing review by the National Research Council.

Top Technology Challenges Defined.

Individual roadmaps for remote sensing Instruments/sensors, observatories, and in-situ instruments/sensors defined with both push and pull technologies highlighted.